

Chapter 16

LINES AND PLANES IN SPACE

EXERCISE 16A.1

- 1 a i $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 3 \\ -4 \end{pmatrix} + t \begin{pmatrix} 1 \\ 4 \end{pmatrix}$ ii $x = 3 + t, y = -4 + 4t, t \in \mathbb{R}$
 b i $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 5 \\ 2 \end{pmatrix} + t \begin{pmatrix} -8 \\ 2 \end{pmatrix}$ ii $x = 5 - 8t, y = 2 + 2t, t \in \mathbb{R}$
 c i $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -6 \\ 0 \end{pmatrix} + t \begin{pmatrix} 3 \\ 7 \end{pmatrix}$ ii $x = -6 + 3t, y = 7t, t \in \mathbb{R}$
 d i $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -1 \\ 11 \end{pmatrix} + t \begin{pmatrix} -2 \\ 1 \end{pmatrix}$ ii $x = -1 - 2t, y = 11 + t, t \in \mathbb{R}$

2 $x = -1 + 2\lambda, y = 4 - \lambda, \lambda \in \mathbb{R}$

When $\lambda = 0, x = -1 + 2(0) = -1$ and $y = 4 - 0 = 4$ \therefore the point is $(-1, 4)$.

When $\lambda = 1, x = -1 + 2(1) = 1$ and $y = 4 - 1 = 3$ \therefore the point is $(1, 3)$.

When $\lambda = 3, x = -1 + 2(3) = 5$ and $y = 4 - 3 = 1$ \therefore the point is $(5, 1)$.

When $\lambda = -1, x = -1 + 2(-1) = -3$ and $y = 4 - (-1) = 5$ \therefore the point is $(-3, 5)$.

When $\lambda = -4, x = -1 + 2(-4) = -9$ and $y = 4 - (-4) = 8$ \therefore the point is $(-9, 8)$.

- 3 a If $t + 2 = 3$ and $1 - 3t = -2$, we get $t = 1$ and $-3t = -3$ $\therefore t = 1$
 Since $t = 1$ in each case, $(3, -2)$ lies on the line.

If $t + 2 = 0$ and $1 - 3t = 6$, we get $t = -2$ and $-3t = 6$ $\therefore t = -\frac{5}{3}$
 $\therefore (0, 6)$ does not lie on the line.

- b If $(k, 4)$ lies on $x = 1 - 2t, y = 1 + t$, then

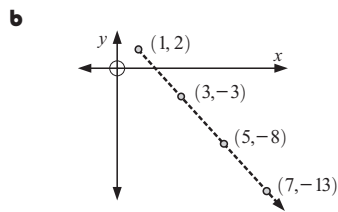
$$k = 1 - 2t \quad \text{and} \quad 4 = 1 + t$$

$$\therefore t = 3$$

$$\text{and } k = 1 - 6 = -5$$

- 4 a $x(0) = 1$ and $y(0) = 2$,
 \therefore the initial position is $(1, 2)$

- c In 1 second, the
 x -step is 2 and y -step is -5 , which is
 a distance of $\sqrt{2^2 + (-5)^2} = \sqrt{29}$ cm
 \therefore the speed is $\sqrt{29}$ cm s $^{-1}$.



EXERCISE 16A.2

- 1 a The vector equation is $\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 3 \\ -7 \end{pmatrix} + t \begin{pmatrix} 2 \\ 1 \\ 3 \end{pmatrix}, t \in \mathbb{R}$

- b The vector equation is $\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix} + t \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix}, t \in \mathbb{R}$

- c Since the line is parallel to the X -axis, it has direction vector $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$

\therefore the vector equation is $\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -2 \\ 2 \\ 1 \end{pmatrix} + t \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, t \in \mathbb{R}$

- 2 a** The parametric equations are:

$$x = 5 + (-1)t, \quad y = 2 + 2t, \quad z = -1 + 6t$$

$$\therefore x = 5 - t, \quad y = 2 + 2t, \quad z = -1 + 6t, \quad t \in \mathbb{R}$$

- b** The parametric equations are:

$$x = 0 + 2t, \quad y = 2 + (-1)t, \quad z = -1 + 3t$$

$$\therefore x = 2t, \quad y = 2 - t, \quad z = -1 + 3t, \quad t \in \mathbb{R}$$

- c** Since the line is perpendicular to the XOY plane, it has direction vector $\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$.

$$\therefore \text{the parametric equations are: } x = 3 + 0t, \quad y = 2 + 0t, \quad z = -1 + 1t$$

$$\therefore x = 3, \quad y = 2, \quad z = -1 + t, \quad t \in \mathbb{R}$$

3 a $\overrightarrow{AB} = \begin{pmatrix} -1-1 \\ 3-2 \\ 2-1 \end{pmatrix} = \begin{pmatrix} -2 \\ 1 \\ 1 \end{pmatrix} \therefore x = 1 - 2t, \quad y = 2 + t, \quad z = 1 + t, \quad t \in \mathbb{R}$

b $\overrightarrow{CD} = \begin{pmatrix} 3-0 \\ 1-1 \\ -1-3 \end{pmatrix} = \begin{pmatrix} 3 \\ 0 \\ -4 \end{pmatrix} \therefore x = 3t, \quad y = 1, \quad z = 3 - 4t, \quad t \in \mathbb{R}$

c $\overrightarrow{EF} = \begin{pmatrix} 1-1 \\ -1-2 \\ 5-5 \end{pmatrix} = \begin{pmatrix} 0 \\ -3 \\ 0 \end{pmatrix} \therefore x = 1, \quad y = 2 - 3t, \quad z = 5, \quad t \in \mathbb{R}$

d $\overrightarrow{GH} = \begin{pmatrix} 5-0 \\ -1-1 \\ 3-(-1) \end{pmatrix} = \begin{pmatrix} 5 \\ -2 \\ 4 \end{pmatrix} \therefore x = 5t, \quad y = 1 - 2t, \quad z = -1 + 4t, \quad t \in \mathbb{R}$

- 4** Given $x = 1 - \lambda$, $y = 3 + \lambda$, $z = 3 - 2\lambda$:

a The line meets the XOY plane when $z = 0 \quad \therefore 3 - 2\lambda = 0$
 $\therefore \lambda = \frac{3}{2}$

Then $x = 1 - \frac{3}{2} = -\frac{1}{2}$ and $y = 3 + \frac{3}{2} = \frac{9}{2}$, so the point is $(-\frac{1}{2}, \frac{9}{2}, 0)$.

b The line meets the YOZ plane when $x = 0 \quad \therefore 1 - \lambda = 0$
 $\therefore \lambda = 1$

Then $y = 3 + 1 = 4$ and $z = 3 - 2 = 1$, so the point is $(0, 4, 1)$.

c The line meets the XOZ plane when $y = 0 \quad \therefore 3 + \lambda = 0$
 $\therefore \lambda = -3$

Then $x = 1 - (-3) = 4$ and $z = 3 - 2(-3) = 9$, so the point is $(4, 0, 9)$.

- 5** Given a line with equations $x = 2 - \lambda$, $y = 3 + 2\lambda$ and $z = 1 + \lambda$,

the distance to the point $(1, 0, -2)$ is $\sqrt{(2 - \lambda - 1)^2 + (3 + 2\lambda - 0)^2 + (1 + \lambda + 2)^2}$.

But this distance = $5\sqrt{3}$ units

$$\therefore \sqrt{(1 - \lambda)^2 + (3 + 2\lambda)^2 + (\lambda + 3)^2} = 5\sqrt{3}$$

$$\therefore (1 - \lambda)^2 + (3 + 2\lambda)^2 + (\lambda + 3)^2 = 75$$

$$\therefore 1 - 2\lambda + \lambda^2 + 9 + 12\lambda + 4\lambda^2 + \lambda^2 + 6\lambda + 9 = 75$$

$$\therefore 6\lambda^2 + 16\lambda - 56 = 0$$

$$\therefore 3\lambda^2 + 8\lambda - 28 = 0$$

$$\therefore (3\lambda + 14)(\lambda - 2) = 0$$

$$\therefore \lambda = -\frac{14}{3} \text{ or } \lambda = 2$$

When $\lambda = 2$ the point is $(0, 7, 3)$, and when $\lambda = -\frac{14}{3}$ the point is $(\frac{20}{3}, -\frac{19}{3}, -\frac{11}{3})$.

- 6 a** Let $A(1 + \lambda, 2 - \lambda, 3 + \lambda)$ be a point on the line such that \overrightarrow{PA} is perpendicular to the line.

$$\text{Then } \overrightarrow{PA} = \begin{pmatrix} 1 + \lambda - 1 \\ 2 - \lambda - 1 \\ 3 + \lambda - 2 \end{pmatrix} = \begin{pmatrix} \lambda \\ 1 - \lambda \\ 1 + \lambda \end{pmatrix}$$

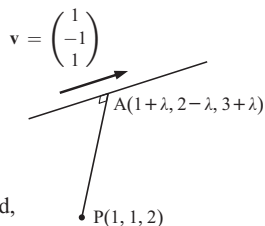
$$\begin{aligned} \text{and } PA &= \sqrt{\lambda^2 + (1 - \lambda)^2 + (1 + \lambda)^2} \\ &= \sqrt{\lambda^2 + (1 - 2\lambda + \lambda^2) + (1 + 2\lambda + \lambda^2)} \\ &= \sqrt{3\lambda^2 + 2} \text{ units} \end{aligned}$$

$[PA]$ is perpendicular to the line when $PA^2 = 3\lambda^2 + 2$ is minimised,

$$\text{which occurs when } \lambda = -\frac{b}{2a} = -\frac{0}{6} = 0$$

\therefore A is at $(1 + 0, 2 - 0, 3 + 0)$

\therefore the foot of the perpendicular is $(1, 2, 3)$.



- b** Let A be a point on the line such that \overrightarrow{PA} is perpendicular to the line.

\therefore A is at $(1 + \mu, 2 - \mu, 2\mu)$ for some μ .

$$\text{Now } \overrightarrow{PA} = \begin{pmatrix} 1 + \mu - 1 \\ 2 - \mu - 1 \\ 2\mu - 3 \end{pmatrix} = \begin{pmatrix} \mu - 1 \\ 1 - \mu \\ 2\mu - 3 \end{pmatrix}$$

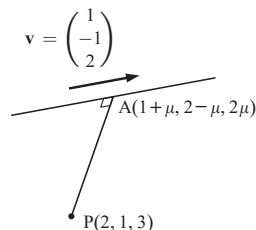
$$\begin{aligned} \text{and } PA &= \sqrt{(\mu - 1)^2 + (1 - \mu)^2 + (2\mu - 3)^2} \\ &= \sqrt{\mu^2 - 2\mu + 1 + 1 - 2\mu + \mu^2 + 4\mu^2 - 12\mu + 9} \\ &= \sqrt{6\mu^2 - 16\mu + 11} \text{ units} \end{aligned}$$

$[PA]$ is perpendicular to the line when $PA^2 = 6\mu^2 - 16\mu + 11$ is minimised,

$$\text{which occurs when } \mu = -\frac{b}{2a} = -\frac{-16}{12} = \frac{4}{3}$$

\therefore A is at $(1 + \frac{4}{3}, 2 - \frac{4}{3}, 2(\frac{4}{3}))$

\therefore the foot of the perpendicular is $(\frac{7}{3}, \frac{2}{3}, \frac{8}{3})$.



EXERCISE 16A.3

- 1** l_1 has direction vector $\begin{pmatrix} 4 \\ -3 \end{pmatrix}$ and l_2 has direction vector $\begin{pmatrix} 5 \\ 4 \end{pmatrix}$. If θ is the angle between them,

$$\cos \theta = \frac{\left| \begin{pmatrix} 4 \\ -3 \end{pmatrix} \cdot \begin{pmatrix} 5 \\ 4 \end{pmatrix} \right|}{\sqrt{16 + 9}\sqrt{25 + 16}} = \frac{|20 + (-12)|}{\sqrt{25 \times 41}} = \frac{8}{\sqrt{25 \times 41}}$$

$$\therefore \theta = \arccos\left(\frac{8}{\sqrt{25 \times 41}}\right) \approx 75.5^\circ$$

\therefore the required angle measures 75.5° .

- 2** l_1 has direction vector $\begin{pmatrix} 12 \\ 5 \end{pmatrix}$ and l_2 has direction vector $\begin{pmatrix} 3 \\ -4 \end{pmatrix}$. If θ is the angle between them,

$$\cos \theta = \frac{\left| \begin{pmatrix} 12 \\ 5 \end{pmatrix} \cdot \begin{pmatrix} 3 \\ -4 \end{pmatrix} \right|}{\sqrt{144 + 25}\sqrt{9 + 16}} = \frac{|36 + (-20)|}{13 \times 5} = \frac{16}{65}$$

$$\therefore \theta = \arccos\left(\frac{16}{65}\right) \approx 75.7^\circ$$

- 3** Line 1 has direction vector $\begin{pmatrix} 5 \\ -2 \end{pmatrix}$ and line 2 has direction vector $\begin{pmatrix} 4 \\ 10 \end{pmatrix}$

$$\text{and } \begin{pmatrix} 5 \\ -2 \end{pmatrix} \cdot \begin{pmatrix} 4 \\ 10 \end{pmatrix} = 20 + (-20) = 0$$

\therefore l_1 and l_2 are perpendicular

4 If $\frac{x-8}{3} = \frac{9-y}{16} = \frac{z-10}{7} = \lambda$ say, then $x = 8 + 3\lambda$, $y = 9 - 16\lambda$, $z = 10 + 7\lambda$

\therefore line 1 has vector $\begin{pmatrix} 3 \\ -16 \\ 7 \end{pmatrix}$ and line 2 has vector $\begin{pmatrix} 3 \\ 8 \\ -5 \end{pmatrix}$. If θ is the angle between them,

$$\cos \theta = \frac{\left| \begin{pmatrix} 3 \\ -16 \\ 7 \end{pmatrix} \cdot \begin{pmatrix} 3 \\ 8 \\ -5 \end{pmatrix} \right|}{\sqrt{9+256+49}\sqrt{9+64+25}} = \frac{|9-128-35|}{\sqrt{314}\sqrt{98}} = \frac{154}{\sqrt{314 \times 98}}$$

$\therefore \theta \approx 28.6^\circ$

EXERCISE 16B.1

- 1 a i When $t = 0$, $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -4 \\ 3 \end{pmatrix}$
 \therefore the object is at $(-4, 3)$.
 ii The velocity vector is $\begin{pmatrix} 12 \\ 5 \end{pmatrix}$.
 iii The speed is $\sqrt{12^2 + 5^2} = 13 \text{ ms}^{-1}$
- b i When $t = 0$, $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ -6 \end{pmatrix}$
 \therefore the object is at $(0, -6)$.
 ii The velocity vector is $\begin{pmatrix} 3 \\ -4 \end{pmatrix}$.
 iii The speed is $\sqrt{3^2 + (-4)^2} = 5 \text{ ms}^{-1}$
- c i When $t = 0$, $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -2 \\ -7 \end{pmatrix}$
 \therefore the object is at $(-2, -7)$.
 ii The velocity vector is $\begin{pmatrix} -6 \\ -4 \end{pmatrix}$.
 iii The speed is $\sqrt{(-6)^2 + (-4)^2} = \sqrt{36 + 16} = \sqrt{52} \text{ ms}^{-1}$

- 2 a $\begin{pmatrix} 4 \\ -3 \end{pmatrix}$ has length $\sqrt{4^2 + (-3)^2} = 5$
 $\therefore 30\begin{pmatrix} 4 \\ -3 \end{pmatrix}$ has length 150
 \therefore the velocity vector is $\begin{pmatrix} 120 \\ -90 \end{pmatrix}$.
- b $\begin{pmatrix} 24 \\ 7 \end{pmatrix}$ has length $\sqrt{24^2 + 7^2} = 25$
 $\therefore \frac{1}{2}\begin{pmatrix} 24 \\ 7 \end{pmatrix}$ has length 12.5
 \therefore the velocity vector is $\begin{pmatrix} 12 \\ 3.5 \end{pmatrix}$.
- c $2\mathbf{i} + \mathbf{j} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$ has length $\sqrt{2^2 + 1^2} = \sqrt{5}$
 $\therefore 10\sqrt{5}\begin{pmatrix} 2 \\ 1 \end{pmatrix}$ has length 50
 \therefore the velocity vector is $\begin{pmatrix} 20\sqrt{5} \\ 10\sqrt{5} \end{pmatrix}$.
- d $-3\mathbf{i} + 4\mathbf{j} = \begin{pmatrix} -3 \\ 4 \end{pmatrix}$ has length $\sqrt{(-3)^2 + 4^2} = 5$
 $\therefore 20\begin{pmatrix} -3 \\ 4 \end{pmatrix}$ has length 100
 \therefore the velocity vector is $\begin{pmatrix} -60 \\ 80 \end{pmatrix}$.

3 Yacht A: $\begin{pmatrix} x_A \\ y_A \end{pmatrix} = \begin{pmatrix} 4 \\ 5 \end{pmatrix} + t\begin{pmatrix} 1 \\ -2 \end{pmatrix}$ Yacht B: $\begin{pmatrix} x_B \\ y_B \end{pmatrix} = \begin{pmatrix} 1 \\ -8 \end{pmatrix} + t\begin{pmatrix} 2 \\ 1 \end{pmatrix}$, $t \geq 0$

a When $t = 0$, $\begin{pmatrix} x_A \\ y_A \end{pmatrix} = \begin{pmatrix} 4 \\ 5 \end{pmatrix}$ \therefore A is at $(4, 5)$
 and $\begin{pmatrix} x_B \\ y_B \end{pmatrix} = \begin{pmatrix} 1 \\ -8 \end{pmatrix}$ \therefore B is at $(1, -8)$.

b For A, the velocity vector is $\begin{pmatrix} 1 \\ -2 \end{pmatrix}$, and for B it is $\begin{pmatrix} 2 \\ 1 \end{pmatrix}$.

c Speed of A = $\sqrt{1^2 + (-2)^2} = \sqrt{5} \text{ km h}^{-1}$. Speed of B = $\sqrt{2^2 + 1^2} = \sqrt{5} \text{ km h}^{-1}$.

d The distance between them is $D = \sqrt{[(1+2t) - (4+t)]^2 + [(-8+t) - (5-2t)]^2}$
 $= \sqrt{(-3+t)^2 + (-13+3t)^2}$
 $= \sqrt{9-6t+t^2 + 169-78t+9t^2}$
 $= \sqrt{10t^2 - 84t + 178}$

This is a minimum when $10t^2 - 84t + 178$ is a minimum. This occurs when

$$t = \frac{-b}{2a} = \frac{84}{20} = 4.2 \text{ hours. } \therefore \text{ the time is 4 h 12 min after 6 am, or 10:12 am.}$$

e A has direction vector $\begin{pmatrix} 1 \\ -2 \end{pmatrix}$ and B has direction vector $\begin{pmatrix} 2 \\ 1 \end{pmatrix}$.

Since $\begin{pmatrix} 1 \\ -2 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ 1 \end{pmatrix} = 2 - 2 = 0$, the paths of the yachts are at right angles to each other.

- 4 a** P has position $\begin{pmatrix} x_1 \\ y_1 \end{pmatrix} = \begin{pmatrix} -5 \\ 4 \end{pmatrix} + t \begin{pmatrix} 3 \\ -1 \end{pmatrix}$ and at $t = 0$, the time is 1:34 pm

$$\therefore x_1(t) = -5 + 3t, \quad y_1(t) = 4 - t.$$

b Speed = $\sqrt{3^2 + (-1)^2} = \sqrt{10} \text{ km min}^{-1}$

- c** Q fires its torpedo after a minutes.

\therefore at time t , its torpedo has travelled for $(t - a)$ minutes.

$$\therefore \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} = \begin{pmatrix} 15 \\ 7 \end{pmatrix} + (t - a) \begin{pmatrix} -4 \\ -3 \end{pmatrix}, \quad t > a$$

$$\therefore x_2(t) = 15 - 4(t - a) \quad \text{and} \quad y_2(t) = 7 - 3(t - a)$$

- d** They meet when $x_1(t) = x_2(t)$ and $y_1(t) = y_2(t)$

$$\therefore -5 + 3t = 15 - 4(t - a) \quad \text{and} \quad 4 - t = 7 - 3(t - a)$$

$$\therefore 7t - 4a = 20 \dots (1) \quad \text{and} \quad 2t - 3a = 3 \dots (2)$$

Solving simultaneously,

$$21t - 12a = 60 \quad 3 \times (1)$$

$$-8t + 12a = -12 \quad (-4) \times (2)$$

$$\text{adding } 13t \quad = 48$$

$$\therefore t = \frac{48}{13} \quad \text{and} \quad 7 \left(\frac{48}{13} \right) - 4a = 20$$

$$\therefore t \approx 3.6923 \quad \therefore 5.8462 = 4a$$

$$\therefore t \approx 3 \text{ min } 41.54 \text{ sec} \quad \therefore a \approx 1.4615 \approx 1 \text{ min } 27.7 \text{ sec}$$

So, as $a \approx 1.4615$, Q fired at 1:35:28 pm, and the explosion occurred at 1:37:42 pm.

- 5 a** $|\mathbf{b}| = \sqrt{(-3)^2 + (-1)^2} = \sqrt{10}$

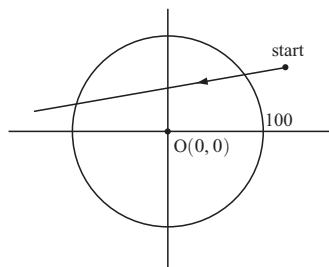
As the speed is $40\sqrt{10} \text{ km h}^{-1}$, the velocity vector is $40 \begin{pmatrix} -3 \\ -1 \end{pmatrix} = \begin{pmatrix} -120 \\ -40 \end{pmatrix}$.

b $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 200 \\ 100 \end{pmatrix} + t \begin{pmatrix} -120 \\ -40 \end{pmatrix}, \quad t \geq 0 \quad \{t = 0 \text{ at } 12:00 \text{ noon}\}$

c At 1:00 pm, $t = 1$ and $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 200-120 \\ 100-40 \end{pmatrix} = \begin{pmatrix} 80 \\ 60 \end{pmatrix}$

- d** The distance from $O(0, 0)$ to $P_1(80, 60)$ is $\left| \begin{pmatrix} 80 \\ 60 \end{pmatrix} \right| = \sqrt{80^2 + 60^2} = 100 \text{ km}$,
which is when it becomes visible to radar. {within 100 km of $O(0, 0)$ }

e



A general point on the path is $P(200 - 120t, 100 - 40t)$.

Now $\vec{OP} = \begin{pmatrix} 200-120t \\ 100-40t \end{pmatrix}$,

and for the closest point $\vec{OP} \bullet \begin{pmatrix} -3 \\ -1 \end{pmatrix} = 0$

$$\therefore -3(200 - 120t) - 1(100 - 40t) = 0$$

$$\therefore -700 + 400t = 0$$

$$\therefore t = \frac{7}{4} = 1\frac{3}{4} \text{ hours}$$

The time when the aircraft is closest is 1:45 pm, and

at this time $\vec{OP} = \begin{pmatrix} 200-120(\frac{7}{4}) \\ 100-40(\frac{7}{4}) \end{pmatrix} = \begin{pmatrix} -10 \\ 30 \end{pmatrix}$

$$\therefore d_{\min} = \sqrt{(-10)^2 + 30^2} \approx 31.6 \text{ km}$$

- f** It disappears from radar when $|\vec{OP}| = 100$ and $t > 1\frac{3}{4}$

$$\therefore \sqrt{(200 - 120t)^2 + (100 - 40t)^2} = 100$$

$$\therefore 40\,000 - 48\,000t + 14\,400t^2 + 10\,000 - 8000t + 1600t^2 = 10\,000$$

$$\therefore 16\,000t^2 - 56\,000t + 40\,000 = 0$$

$$\therefore 16t^2 - 56t + 40 = 0 \quad \{ \div 1000 \}$$

$$\therefore 2t^2 - 7t + 5 = 0 \quad \{ \div 8 \}$$

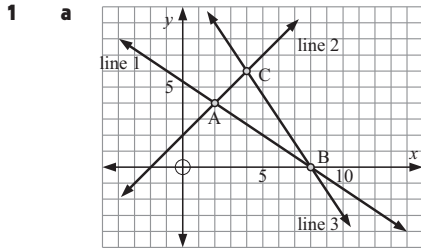
$$\therefore (2t - 5)(t - 1) = 0$$

$$\therefore t = \frac{5}{2} \quad \{ \text{as } t > 1\frac{3}{4} \}$$

So, the aircraft disappears from the radar screen $2\frac{1}{2}$ hours after noon, or at 2:30 pm.

- 6 For A, $x_A(t) = 3 - t$, $y_A(t) = 2t - 4$ For B, $x_B(t) = 4 - 3t$, $y_B(t) = 3 - 2t$
- a When $t = 0$, $x_A(0) = 3$, $y_A(0) = -4$ and $x_B(0) = 4$, $y_B(0) = 3$
 \therefore A is at $(3, -4)$. \therefore B is at $(4, 3)$.
- b The velocity vector of A is $\begin{pmatrix} -1 \\ 2 \end{pmatrix}$ and the velocity vector of B is $\begin{pmatrix} -3 \\ -2 \end{pmatrix}$.
- c If the angle is θ , $\begin{pmatrix} -1 \\ 2 \end{pmatrix} \bullet \begin{pmatrix} -3 \\ -2 \end{pmatrix} = \sqrt{1+4}\sqrt{9+4} \cos \theta$
 $\therefore 3 - 4 = \sqrt{5}\sqrt{13} \cos \theta$
 $\therefore \frac{-1}{\sqrt{65}} = \cos \theta$ and so $\theta \approx 97.1^\circ$
- d If D is the distance between them, then
 $D = \sqrt{[(4 - 3t) - (3 - t)]^2 + [(3 - 2t) - (2t - 4)]^2}$ and D is a minimum when
 $= \sqrt{[1 - 2t]^2 + [7 - 4t]^2}$ $t = -\frac{b}{2a} = \frac{60}{40} = 1\frac{1}{2}$
 $= \sqrt{1 - 4t + 4t^2 + 49 - 56t + 16t^2}$ $\therefore t = 1.5$ hours
 $= \sqrt{20t^2 - 60t + 50}$

EXERCISE 16B.2



- 1 a b A is $(2, 4)$, B is $(8, 0)$, C is $(4, 6)$
- c $BC = \sqrt{(8 - 4)^2 + (0 - 6)^2} = \sqrt{16 + 36} = \sqrt{52}$ units
 $AB = \sqrt{(8 - 2)^2 + (0 - 4)^2} = \sqrt{36 + 16} = \sqrt{52}$ units
 $\therefore BC = AB$ and so $\triangle ABC$ is isosceles.

d Line 1 and Line 2 meet at A.
 $\therefore \begin{pmatrix} -1 \\ 6 \end{pmatrix} + \begin{pmatrix} 3r \\ -2r \end{pmatrix} = \begin{pmatrix} 0 \\ 2 \end{pmatrix} + s \begin{pmatrix} 1 \\ 1 \end{pmatrix}$
 $\therefore \begin{pmatrix} 3r - s \\ -2r - s \end{pmatrix} = \begin{pmatrix} 1 \\ -4 \end{pmatrix}$
 $\therefore 3r - s = 1$
 and $2r + s = 4$
 Adding, $5r = 5 \quad \therefore r = 1$
 $\therefore \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -1 \\ 6 \end{pmatrix} + \begin{pmatrix} 3 \\ -2 \end{pmatrix} = \begin{pmatrix} 2 \\ 4 \end{pmatrix} \quad \checkmark$

Line 2 and Line 3 meet at C.
 $\therefore \begin{pmatrix} 0 \\ 2 \end{pmatrix} + s \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 10 \\ -3 \end{pmatrix} + t \begin{pmatrix} -2 \\ 3 \end{pmatrix}$
 $\therefore \begin{pmatrix} s + 2t \\ s - 3t \end{pmatrix} = \begin{pmatrix} 10 \\ -5 \end{pmatrix}$
 $\therefore s + 2t = 10$
 $\quad \quad \quad -s + 3t = 5$
 Adding, $5t = 15 \quad \therefore t = 3$
 $\therefore \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 10 \\ -3 \end{pmatrix} + 3 \begin{pmatrix} -2 \\ 3 \end{pmatrix} = \begin{pmatrix} 4 \\ 6 \end{pmatrix} \quad \checkmark$

Line 1 and Line 3 meet at B.
 $\therefore \begin{pmatrix} -1 \\ 6 \end{pmatrix} + r \begin{pmatrix} 3 \\ -2 \end{pmatrix} = \begin{pmatrix} 10 \\ -3 \end{pmatrix} + t \begin{pmatrix} -2 \\ 3 \end{pmatrix}$
 $\therefore \begin{pmatrix} 3r + 2t \\ -2r - 3t \end{pmatrix} = \begin{pmatrix} 11 \\ -9 \end{pmatrix}$
 $\therefore 3r + 2t = 11 \quad \dots (1)$
 $\quad \quad \quad -2r - 3t = -9 \quad \dots (2)$
 $\therefore 9r + 6t = 33 \quad \{3 \times (1)\}$
 $\quad \quad \quad -4r - 6t = -18 \quad \{2 \times (2)\}$
 Adding, $5r = 15$
 $\therefore r = 3$
 So, $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -1 \\ 6 \end{pmatrix} + 3 \begin{pmatrix} 3 \\ -2 \end{pmatrix} = \begin{pmatrix} 8 \\ 0 \end{pmatrix} \quad \checkmark$